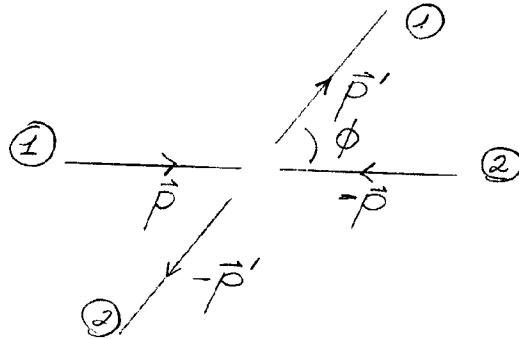


HOMEWORK 11 - PROBLEM 32

PREPARED BY PEKAREWICZ
APR 13 2002



VIEW OF THE COLLISION FROM THE CENTER OF MOMENTUM (COM) FRAME.

IN THIS FRAME THE FOUR MOMENTUM OF THE PARTICLES BEFORE AND AFTER THE COLLISION ARE GIVEN BY:

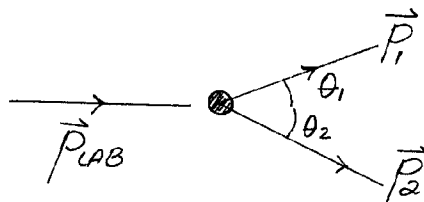
$$p_1^M = (E, p, 0, 0) \quad ; \quad p_1'^M = (E, p \cos \phi, p \sin \phi, 0)$$

$$p_2^M = (E, -p, 0, 0) \quad ; \quad p_2'^M = (E, -p \cos \phi, -p \sin \phi, 0)$$

WHERE ENERGY-MOMENTUM CONSERVATION DEMANDS:

$$|\vec{p}'| = |\vec{p}| \equiv p = m\gamma\beta \quad \text{AND} \quad E = m\gamma \quad (\text{I AM USING } c=1)$$

THE SAME COLLISION IN THE LABORATORY FRAME LOOKS LIKE:



VIEW OF THE COLLISION FROM THE LABORATORY (LAB) FRAME.

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DATE	

TO TRANSFORM THE FOUR MOMENTA FROM THE "COM" FRAME TO THE "LAB" FRAME WE JUST USE THE FOLLOWING LORENTZ TRANSFORMATION

$$A = \begin{pmatrix} \gamma & \beta\gamma & 0 & 0 \\ \beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

CLEARLY, UNDER THIS TRANSFORMATION P_2^M (THE FOUR MOMENTUM OF THE TARGET PARTICLE) GOES TO:

$$P_2^M /_{LAB} = \begin{pmatrix} \gamma & \beta\gamma & 0 & 0 \\ \beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E \\ -p \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma E - \beta\gamma p \\ \beta\gamma E - \gamma p \\ 0 \\ 0 \end{pmatrix}$$

BUT...

$$\begin{aligned} \gamma E - \beta\gamma p &= \gamma m\gamma - \beta\gamma m\gamma\beta = m\gamma^2(1 - \beta^2) = m \\ \beta\gamma E - \gamma p &= \beta\gamma^2 m - \gamma m\gamma\beta = 0 \end{aligned}$$

HENCE, AS EXPECTED UNDER THIS LORENTZ TRANSFORMATION $P_2^M /_{LAB} = \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix}$.

WE NOW TRANSFORM P_1^M AND P_2^M ; THAT IS,

$$P_1^M /_{LAB} = \begin{pmatrix} \gamma & \beta\gamma & 0 & 0 \\ \beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E \\ p \cos\phi \\ p \sin\phi \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma E + \beta\gamma p \cos\phi \\ \beta\gamma E + \gamma p \cos\phi \\ p \sin\phi \\ 0 \end{pmatrix}$$

AND

$$P_2^M /_{LAB} = \begin{pmatrix} \gamma & \beta\gamma & 0 & 0 \\ \beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E \\ -p \cos\phi \\ -p \sin\phi \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma E - \beta\gamma p \cos\phi \\ \beta\gamma E - \gamma p \cos\phi \\ -p \sin\phi \\ 0 \end{pmatrix}$$

PREPARED BY	
DATE	

IN THIS WAY,

$$\tan \theta_1 = \frac{(P'_1)_y}{(P'_1)_x} \Big|_{LAB} = \frac{p \sin \phi}{\beta \gamma E + \gamma p \cos \phi} = \frac{m \gamma \beta \sin \phi}{m \gamma^2 \beta + m \gamma^2 \beta \cos \phi} = \frac{\sin \phi}{\gamma (1 + \cos \phi)}$$

SIMILARLY, (DEFINING θ_2 AS IN THE FIGURE)

$$\tan \theta_2 = \frac{(P'_2)_y}{(P'_2)_x} \Big|_{LAB} = \frac{p \sin \phi}{\beta \gamma E - \gamma p \cos \phi} = \frac{m \gamma \beta \sin \phi}{m \gamma^2 \beta - m \gamma^2 \beta \cos \phi} = \frac{\sin \phi}{\gamma (1 - \cos \phi)}$$

SINCE WE HAVE ALREADY COMPUTED THE TANGENT OF BOTH ANGLES LET'S COMPUTE THEIR SUM THROUGH:

$$\begin{aligned} \tan(\theta) &= \tan(\theta_1 + \theta_2) = \frac{\tan \theta_1 + \tan \theta_2}{1 - \tan \theta_1 \tan \theta_2} \\ &= \frac{\frac{\sin \phi}{\gamma (1 + \cos \phi)} + \frac{\sin \phi}{\gamma (1 - \cos \phi)}}{1 - \frac{\sin^2 \phi}{\gamma^2 (1 - \cos^2 \phi)}} = \frac{\frac{2 \sin \phi}{\gamma \sin^2 \phi}}{\frac{\gamma^2 - 1}{\gamma^2}} \end{aligned}$$

OR USING,

$$\gamma^2 - 1 = \frac{1}{1 - \beta^2} - 1 = \beta^2 \gamma^2$$

WE OBTAIN

$$\tan \theta = \frac{2}{\gamma \beta^2 \sin \phi}$$

PREPARED BY	
DATE	

SOME NUMBERS...

β	ϕ	Q_1	Q_2	θ
0.01	15	7.50	82.50	90.00
	30	15.00	75.00	90.00
	60	30.00	60.00	90.00
	90	45.00	45.00	90.00
0.99	15	1.06	46.98	48.04
	30	2.17	27.77	29.93
	60	4.66	13.73	18.39
	90	8.03	8.03	16.06

HOMEWORK II - PROBLEM 33

PREPARED BY PEKAREVICZ
 DATE APR 13 2002

LET US RECALL THAT THE FOUR-VECTORS A^M AND ∂^M ARE GIVEN BY:

$$A^M = \begin{pmatrix} \Phi \\ \vec{A} \end{pmatrix} \text{ AND } \partial^M = \begin{pmatrix} \frac{1}{c} \frac{\partial}{\partial t} \\ -\vec{\nabla} \end{pmatrix}$$

IN THIS WAY WE OBTAIN:

$$F_{0i} = \partial_c A_i - \partial_i A_0 = -\frac{1}{c} \frac{\partial A_i}{\partial t} - (\nabla \phi)^i = E^i$$

AND

$$F_{ij} = \partial_i A_j - \partial_j A_i = -\frac{\partial A_j}{\partial x^i} + \frac{\partial A_i}{\partial x^j} = -\epsilon_{ijk} B^k$$

SO THAT

$$F_{\mu\nu} = \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{pmatrix}$$

THE TENSOR DUAL TO $F_{\mu\nu}$ IS DEFINED AS,

$$G^{\mu\nu} \equiv \frac{1}{2} \epsilon^{\mu\alpha\beta\gamma} F_{\alpha\beta}$$

THEN,

$$G^{0i} = \frac{1}{2} \epsilon^{0i\alpha\beta} F_{\alpha\beta} = \frac{1}{2} \epsilon^{0ijk} F_{jk} = \frac{1}{2} \epsilon_{ijk} (-\epsilon_{jkl} B^l) = -B_i$$

AND

$$G^{ij} = \frac{1}{2} \epsilon^{ij\alpha\beta} F_{\alpha\beta} + \frac{1}{2} \epsilon^{ij\gamma\delta} F_{\gamma\delta} = \epsilon^{0ijk} F_{0k} = +\epsilon_{ijk} E_k$$

OR

$$G^{\mu\nu} = \begin{pmatrix} 0 & -B_x & -B_y & -B_z \\ B_x & 0 & E_z & -E_y \\ B_y & -E_z & 0 & E_x \\ B_z & E_y & -E_x & 0 \end{pmatrix}$$

HOMEWORK II - PROBLEM 34

a)

WE HAVE COMPUTED IN PROBLEM 34:

$$F_{\mu\nu} = \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{pmatrix}; \quad F^{\mu\nu} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{pmatrix}$$

AND

$$G_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & B_x & B_y & B_z \\ -B_x & 0 & E_z & -E_y \\ -B_y & -E_z & 0 & E_x \\ -B_z & E_y & -E_x & 0 \end{pmatrix}; \quad G^{\mu\nu} = \begin{pmatrix} 0 & -B_x & -B_y & -B_z \\ B_x & 0 & E_z & -E_y \\ B_y & -E_z & 0 & E_x \\ B_z & E_y & -E_x & 0 \end{pmatrix}$$

HENCE,

$$\begin{aligned} F^{\mu\nu} F_{\mu\nu} &= -F^{\mu\nu} F_{\nu\mu} = -\text{Tr}(F^\uparrow F_\downarrow) = \\ &= -(E^2 + E_x^2 - B_z^2 - B_y^2 + E_y^2 - B_z^2 - B_x^2 + E_z^2 - B_y^2 - B_x^2) \\ &= 2(B^2 - E^2) \end{aligned}$$

AND

$$\begin{aligned} G^{\mu\nu} G_{\mu\nu} &= -G^{\mu\nu} G_{\nu\mu} = -\text{Tr}(G^\uparrow G_\downarrow) = \\ &= -(B^2 + B_x^2 - E_z^2 - E_y^2 + B_y^2 - E_z^2 - E_x^2 + B_z^2 - E_y^2 - E_x^2) \\ &= 2(E^2 - B^2) \end{aligned}$$

AND

$$\begin{aligned} F^{\mu\nu} G_{\mu\nu} &= -F^{\mu\nu} G_{\nu\mu} = -\text{Tr}(F^\uparrow G_\downarrow) = \\ &= -(\vec{E} \cdot \vec{B} + \vec{E} \cdot \vec{B} + \vec{E} \cdot \vec{B} + \vec{E} \cdot \vec{B}) \\ &= -4\vec{E} \cdot \vec{B} \end{aligned}$$

OR

$$\begin{aligned} F^{\mu\nu} F_{\mu\nu} &= 2(B^2 - E^2) = -G^{\mu\nu} G_{\mu\nu} \\ F^{\mu\nu} G_{\mu\nu} &= -4\vec{E} \cdot \vec{B} \end{aligned}$$

PREPARED BY	
DATE	

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b) Impossible! We have just shown that $E^2 - B^2$ is a Lorentz invariant. Thus, if in the first frame $\vec{E} \neq 0$ and $\vec{B} = 0$, so that $\vec{E}^2 - \vec{B}^2 > 0$; then, $\vec{E}^2 - \vec{B}^2$ must be greater than zero in all frames.